

In the Claims:

1     1.     (original) A method for synchronizing the position (LH) of  
2           the steering handle (8) and the steering angle (LW) which  
3           has been set at the steered vehicle wheels (1) for steering  
4           with a relationship function which can be set between the  
5           handle position (LH) and the steering angle (LW) by means  
6           of an open-loop or closed-loop control device (13; 18),  
7           characterized in that after the open-loop or closed-loop  
8           control device (13; 18) has been activated the  
9           instantaneous handle position (LH) and the instantaneous  
10          steering angle (LW) are compared taking into account the  
11          instantaneously set relationship function, and in the case  
12          of a deviation (S) in position a relative adjustment is  
13          carried out in order to reduce the deviation (S) in  
14          position between the handle position (LH) and the steering  
15          angle (LW).

1     2.     (original) The method as claimed in claim 1, characterized  
2           in that the relative adjustment takes place only if an  
3           interrogation criterion is fulfilled after or during the  
4           activation of the open-loop control device.

Claims 3 to 12 (canceled).

**[REMARKS FOLLOW ON NEXT PAGE]**